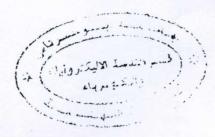
Ministry of Higher Education and Scientific Research



University "M'Hamed Bouguerra" of Boumerdes

Faculty of Engineering

Department of Electrical and Electronic Engineering (DGEE)



DEUA Program

OCTOBER 2001

Ministry of Higher Education and Scientific Research

University of Boumerdes Faculty of Engineering

Tel/Fax: (213) (0) 24 81 83 33



Department of Electrical & Electronic Engineering

Nº

/CDGEE/2002

DEUA Program

First Year (Common Core)

Semester	Code	Course Title	Credit	Lec.	Load Rec.	Lab.	LPW	Remark
1	TS111	English I	6	24	0	0	24	24 h/week
2	TE101 TE171	English II Electric Circuits I (DC) Applied Mathematics Applied Physics	3 3 3 4	12rs 3 3 3 3	0 1h30 1h30 1h30	0 1h30 0 3	12 6 4h30 7h30	30h /week
	TEITE	Total		24/21	0/4.5	0/4.5	24/30	

Second Year (2)

Year	Code	Course Title	Credit	Lec.	Load Rec.	Lab.	LPW	Remark
	TT204	Electric Draft and Printed Circuits	2	1h30	0	1h30	3	
	TE241 Fundamental and Linear Integrated Electronics. TE221 Digital Electronics	4	3	1h30	1h30	6	30 weeks	
П		Digital Electronics	4	3	0	3	6	25h30/week
11			3	1h30	0	1h30	3	2311307 WCCK
	TE231	1	4	3	1h30	1h30	6	
	TE291	Management (Maintenance, Industrial)	2	1h30	0	0	1h30	
		Total		13.5	3h	9h	25h30	

University of Boumerdes, Faculty of Engineering, Department of Electrical and Electronic Engineering.

Third Year (3) DEUA, option: Digital.

X

Semester	Code	Course Title	Credit	Lec.	Load Rec.	Lab.	LPW	Remark	
	TE224	Introduction to Computer Technology	3	1h30	1h30	1h30	4h30	151	
	TE321	Microprocessors	4	3	0	3	6	15 weeks	
	TE322	Digital Systems Troubleshooting	2	1h30	0	3	4h30	251 221	
6	TE324	Programmable Controllers	3	1h30	1h30	1h30	4h30	25h30/week	
	TE332	Power Electronics	4	3	0	3	6		
	TS313	English III (Technical Report Writing)	3	1h30	1h30	0	3 -		
	TE318	Digital Communications	4	3	0	3	6		
	TE323	Industrial Process Control	4	3	0	3	6	14 weeks	
	TE325	Special Topics on Computers .	3	1h30	0	1h30	3		
	TE382	Project	-	-	_	-	-	18h00/week	
		Industrial Training	-	-	-	_	· - :		
		Total		10.5/9	3/1.5	12/7.5	25.5/18		

Third Year (3) DEUA, option: Electronic Maintenance.

Semester	Code	Course Title	Credit	Lec.	Load Rec.	Lab.	LPW	Remark
	TE312	Electronic Communications *	4	3	0	3	6	15 weeks
	TE321	Microprocessors	4	3	0	3	6	
	TE332		4	3	0	3	6	28h30 /week
5	TE345	Electronic Maintenance and Methodology	4.	3	0	3	6	
	TE351	Instrumentation and Metrology	4	3	0	1h30	4h30	
	TS313	English III (Technical Report Writing)	3	1h30	1h30	0	3	
	TE323	Industrial Process Control	4	3	0	3	3	14 weeks
	TE352	Electronic Equipment Maintenance	2	3	0	0	3	
6	TE382	Project	-	-	-	-	-	09h00 /week
		Industrial Training	-	-	-	-	_	
40		Total		15/7.5	0/1.5	13.5/3	28.5/9	

Third Year (3) DEUA, option: Power.

Semester	Code	Course Title	Credit	Lec.	Load Rec.	Lab.	LPW	Remark	
	TE321	Microprocessors	4	3	0	3	6	15	
	TE331	Power System Components	4	3	0	1h30	4h30	15 weeks 28h30 /week	
	TE332	Power Electronics	4	3	. 0	3	6		
5	TE333	Electric Machines	4	3	0	3	6		
	TE336	Electric Design and Drafting	4	3	0	3	6		
	TS313	English III (Technical Report Writing)	3	1h30	1h30	0	3		
6	TE334	Generation/Transmission & Distribution of Electric Energy	4	3	0	3	6	14 weeks	
	TE335	Methodology and Maintenance	2	1h30	0	1h30	3	12h00 /week	
	TE382	Project		-	-	-	-	121100 / Week	
	_	Industrial Training		-	-	-	-		
		Total		15/6	0/1.5	13.5/4 5	28.5/12		

TE101 Electric Circuits I

Year: one Semester: 02

Credit/Lec./Rec./Lab. 3/3/1.5/1.5

Outline

- I- Series and Parallel Circuits
- II- General Mesh and Node Analysis
- III- Network Theorems
- IV- Capacitance Circuits
- V- Magnetic Circuits
- VI- Inductive Circuits
- VII- Sinusoids and Phasors
- VIII- Series and Parallel AC Circuits
- IX- More Complex AC Circuits

Laboratory:

- 1- Measurement in DC circuits with analog and digital meters
- 2- Verification of circuit theorem
- 3- The oscilloscope and its use to measure simple transients
- 4- AC measurements of RMS values and phase
- 5- Verification of circuit theorem in AC circuits
- 6- Phasor diagrams

TE171 Applied Mathematics

Year : one Semester: 02

Credit/Lec./Rec./Lab. 3/3/1.5/0

Outline

- I- Complex Numbers
- II- Graphs of Applied Trigonometric Functions
- III- Hyperbolic Functions
- IV- Derivatives
- V- Applications of the Derivatives
- VI- Integration
- VII- Applications of Integration
- VIII- Functions of Two Independent Variables Introduction
- IX- Differential Equations
- X- Laplace Transform
- XI- Applications of Laplace Transform
- XII- Matrices Introduction

TE172 Applied Physics

Year: one Semester: 02

Credit/Lec./Rec./Lab. 4/3/1.5/3

- I- Electromagnetism
 - 1.1- Ampere's law
 - 1.2- Biot-Savart law
 - 1.3- Magnetic fields due to current carrying conductors
 - 1.4- Solenoidal currents
 - 1.5- Magnetic flux and flux density
 - 1.6- Electromagnetic induction
- II- Applied Optics
 - 2.1- Image formation
 - 2.2- Equations
 - 2.3- Ray diagrams and aberrations in a thin single lens
 - 2.4- Compound lens
 - 2.5- Camera F-number
 - 2.6- Exposure time, film speed and their relation
- III- Thermodynamics
 - 3.1- Temperature variation of pressure resistance
 - 3.2- Absolute scale of temperature
 - 3.3- Conduction of heat
 - 3.4- Convection currents
 - 3.5- Spectrum and power distribution in black body radiation
 - 3.6- Photometry
- IV- Waves
 - 4.1- Periodic motion
 - 4.2- Simple harmonic motion and its characteristics
 - 4.3- Graphical representation and equation of simple harmonic motion
 - 4.4- Stroboscope, its principle and uses
- V- Wave Optic and Atomic Physics
 - 5.1- Wave nature of light
 - 5.2- Diffraction of light and grating spectrometer
 - 5.3- Spectral series
 - 5.4- Atomic structure
 - 5.5- Energy levels and atomic transitions
 - 5.6- Fluorescence

- 71- Semiconductor Physics
 - 6.1- Structure of solids
 - 6.2- Band theory of solids
 - 6.3- Semiconductors
 - 6.4- Charge carriers idea of holes
 - 6.5- Intrinsic and impurity semiconductors
 - 6.6- P-N junction
 - 6.7- Forward and reverse bias
 - 6.8- Junction transistors

- 1- Field lines of magnets and force on a solenoid plunger
- 2- Experimental study of various aspects of image formation by converging lens
- 3- Temperature variation of resistance and pressure
- 4- Photometry
- 5- Use of stroboscope as tachometer and for studying wave motion
- 6- Measurement of wavelengths of light from different sources of light and phosphors
- 7- Measurement of resistance of semiconductor diodes in reverse and forward bias

TT204 Printed Circuit Boards

Year : two

Semesters: 03 and 04

Credit/Lec./Rec./Lab. 2/1.5/0/1.5

Outline

Printed Circuits Boards

- Introduction 1.1-
- Classification of PCB 1.2-
- Insulating base material 1.3-
- Conducting foil 1.4-
- bonding 1.5-

PCB Design and Layout

- Grid and reduction factor 2.1-
- Component positioning 2.2-
- Drafting aids 2.3-
- Artwork construction: single sided, double sided 2.4-

PCB Processing ILI-

- Photographic reduction 3.1-
- Film processing 3.2-
- Photosensitizing PCB, exposure and developing 3.3-
- 3.4-Etching
- Drilling 3.5-
- Surface cleaning 3.6-
- Plating and sealing 3.7-

Component Assembly IV-

- Standard solar terminals 4.1-
- Solder-less terminals 4.2-
- 4.3-Connectors
- Interfacial connections for double sided boards 4.4-
- Component assembly 4.5-
- Device assembly 4.6-
- Device sockets 4.7-
- 4.8-Heat sinking

Soldering

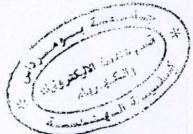
- Characteristics of solder and flux 5.1-
- Soldering iron 5.2-
- Soldering technique 5.3-
- 5.4-Desoldering
- Dip and wave soldering 5.5-

.11-Chassis Mounting

- Common hardware and tools 6.1-
- Special hardware and fasteners 6.2-

- 1- Space allotment and component positioning
- 2- Detailed drawing single sided PCB
- 3- Artwork construction single sided PCB
- 4- Detailed drawing double sided PCB
- 5- Artwork construction double sided PCB
- 6- Project space allotment and component positioning
- *i* Project detailed drawing
- 8- Project artwork master
-)- Photographic reduction and film processing
- 10- PCB Photosensitizing, exposure and developing
- 11- PCB etching and drilling
- 12- Conductor pattern cleaning and plating
- '3- Hardware and component assembly
- i4- Soldering and desoldering
- 15- Chassis design and fabrication
- 6- PCB mounting on chassis
- 7- Interconnection wiring

Testing



2241 Fundamental and Linear Integrated Electronics car : two Hemesters: 03 and 04 redit/Lec./Rec./Lab. 4/3/1.5/1.5 Outline Semiconductor Diodes: Characteristics and Parameters of Ideal and Practical Signal diode 1.1-Rectifier diode 1.2-Schottky diode 1.3-Zener diode 1.4-Diode Applications Discussion on various uses of diodes 2.1 Principles of rectification with resistive load 2.2 Emphasis on waveforms and device ratings 2.3 2.3.1- Single phase: half wave, full wave center tap, full wave bridge 2.3.2- Three phase: half wave Circuit performance figures: ripple factor, etc... 2.4 Principles of Simple Smoothing Circuits Zener Diode Regulator iV-Zener regulator circuits 4.1-Emphasis on the practical variations from the ideal device and ratings 4.2-Transistors Operation and characteristics of bipolar and F.E.T. devices 5.1-Device parameters and manufacturer's data sheets 5.2-Emphasis on the different parameter specifications for amplification, 5.3switching, high frequency operation Transistor equivalent circuit including high frequency effect 5.4-Transistor modes of operation 5.5-Darlington connection 5.6-VI-Transistor Applications Discussion on the various uses of transistors 6.1-Principles of amplification 6.2-Basics of class "A", "B", and "C" amplifiers 6.3-Brief discussion on bias networks 6.4-AC/DC load lines techniques: resistive and transformer coupled loads 6.5-VII-Class A Amplifiers 7.1-Principles 7.2-Distortion Efficiency 7.3-Thermal performance of devices 7.4-Amplifier specification: Zin, Zout, Av, A_I, A_P 7.5-Decibel (dB) notation 7.6-

1		
VIII-	Principl	es and Use of Integrated Circuits (ICs)
IX-	9.1-	ed Circuit Amplifiers Audio
	9.2-	Power
1	9.3-	High frequency
X-	Negativ	ve Feedback
	1().1-	Network interconnection with reasons and performance
_	10.2-	Effects of negative feedback on
		10.2-1. Gain and gain stability
		10.2-2. Distortion
		10.2-3. Bandwidth
		10.2-4. Noise
_ XI-	Operati	ional Amplifiers
	11.1-	Characteristics of ideal and practical op-amps
	11.2-	Summary of available op-amps
	11.3-	Modes of op-amp operation: inversion, non-inversion, differential
	11.4-	Performance calculations of simple circuits
	11.5-	Practical characteristics of op-amps
7		11.5-1. Frequency compensation
		11.5-2. Voltage and current offset
		11.5-3. Drift
		11.5-4. Slew rate
XII-	Op-An	nps Applications
_		Discussion on the various applications of op-amps
	12.2-	Discussion on particular circuits
		12.2-1. Adders
		12.2-2. Multipliers
		12.2-3. Integrators
		12.2-4. Linear and nonlinear gain control
		12.2-5. Unity follower
		12.2-6. Audio mixing
t 377		12.2-7. Log amplifier 12.2-8. Active rectifier circuits
4		
F=3		
V.		12.2-12. Low pass active filters 12.2-13. High pass active filters
17		12.2-13. High pass active filters
T _{XIII} -	Clase	B Amplifiers
_ //11/-	13.1-	Transformer coupled push-pull amplifier
P	13.2-	Cross-over distortion and how to reduce it
	13.3-	Mathematical representation of power and efficiency
	13.4-	Transistor dissipation and the selection of heat sinks
	13.4-	Comparison between push-pull using single and "split" power supplies
	13.5-	Bias networks for class A-B using resistors, diodes and op-amps
	1.7.0-	Thus networks for class I. Is along the

- Complementary-symmetry and quasi complementary-symmetry output stages including Darlington connections Effects of matching and mismatching amplifier to load 13.9- Short circuit and overload protection 13.10- IC power amplifier Class C Power Amplifiers 14.1- Principles of class C Tuned class C circuits 14.2-Mathematical representation of power and efficiency 14.3-14.4- Transistor dissipation Power Supplies XV-15.1- Smoothing networks for rectifier circuits Block diagram of regulated power supply 15.3- Principles of transistor series and shunt regulators 15.4- Power supply specifications: regulation, efficiency, ripple, output impedance 15.5- Methods of measurements of specification parameters 15.6- Effects of open circuit and short circuit load conditions 15.7- Current limiting networks 15.8- Ripple reduction networks 15.9- Use of Darlington interconnection 15.10- Feedback loops with discrete devices and op-amps 15.11- Thermal problems and heat sink selection IC Voltage Regulators 16.1- Survey of available ICs: fixed and variable voltage regulators Heat sink selection Application of IC regulators: current source, high current regulators, adjustable 16.3output voltage from fixed IC regulator, variable output voltage from fixed IC regulator, high output voltage regulator, high input voltage regulator, dual tracking regulator IC regulator protection: current limiting shutdown, thermal shutdown XVII- Oscillators 17.1- Principles of positive feedback 17.2- Barkhausen conditions for oscillation 17.3- Frequency selective network Gain/frequency and phase/frequency plots 17.4-17.5-Principles of operation of the oscillators: 17.5-1. RC phase shift 17.5-2. Wien-bridge
 - Comparison between discrete and op-amps circuits 17.7-Automatic gain control circuits

17.5-3. Hartley 17.5-4. Colpits 17.5-5. Crystal

- 1- Diode characteristics
- = 2- Single phase rectifier circuits with resistive loads
- 3- Zener diode regulator
 - Bias networks
- Class "A" transistor amplifier
 - Effects of negative feedback on class A amplifier gain and gain stability
 - 7- Class C transistor tuned amplifier
- 78- Rectifier circuits with capacitance filters,
 - 1)- Transistor series regulator discrete system, transistor series regulator using op-amps
 - :-- Op-amp characteristics measurements
- :- Applications of op-amps
 - 12-Oscillator circuits

Department of Electrical and Electronic Engineering, **TE221 Digital Electronics** Year : two Semesters: 03 and 04 Credit/Lee./Ree./Lab. 4/3/0/3 Outline Binary Arithmetic Boolean Algebra 111-Logic Gates 3.1-Combinational logic 3.2-Families Astable, Monostable, Schmitt Trigger Flip-flops 5.1-SR 5.2-D 5.3-JK 5.4master-slave Counters 6.1-Ripple counters 6.2-Synchronous counters 6.3-IC counters 6.4-Up/down counters 6.5-Counter design Shift Registers 7.1-Left (L)/right (R) shift register 7.2-Serial in parallel out (SIPO) 7.3-Parallel in serial out (PISO) 7.4-Parallel in parallel out (PIPO) 7.5-Universal shift register VIII-Encoders, Decoders 8.1-Binary to decimal conversion 8.2-Decimal to binary conversion 8.3-Excess-3 code Multiplexers, Demultiplexers Memory Devices 10.1- Volatile memory 10.2- Permanent (nonvolatile) memory 10.3- Memory system

- XI- Optical Electronics
 - 11.1- Decoder/driver
 - 11.2- Seven-segment display
 - 11.3- Dot matrix
- XII- Arithmetic Circuits
 - 12.1- Half-adder
 - 12.2- Full-bit binary adder
 - 12.3- Examples adder circuits
 - 12.4- Binary multiplication
 - 12.5- 74181 Arithmetic logic unit (ALU)
- XIII- Semiconductor Technology and Applications

- 1- Basic logic functions
- 2- Simplification of combinational logic circuits
- 3- counters
- 4- Shift registers
- 5- Decoders and encoders
- 6- Multiplexers and demultiplexers
- 7- Timing circuits
- 8- ALU
- 9- Memory organization
- 10-Displays

TE221 Computer Programming

Year : two

'Semesters: 03 and 04

Credit/Lec./Rec./Lab. 3/1.5/0/1.5

Outline

- 1- Introduction
 - 1.1- Computer types
 - 1.2- Machine and assembly language
 - 1.3- High level language
 - 1.4- Single and multi-user (time-sharing) systems
- II- Flowchart and Algorithm
 - 2.1- Symbols for input/output
 - 2.2- Begin/end
 - 2.3- Processing
 - 2.4- Decision
 - 2.5- Flow line and connector
 - 2.6- Examples
- III- Representation of Constants, Variables and Expressions
 - 3.1- Basic/Pascal statements
 - 3.2- Display and printer control
 - 3.3- Programming examples
- IV- Transfer Statements
 - 4.1- Unconditional branch statements
 - 4.2- IF-THEN-ELSE statements
 - 4.3- Other conditional branch statements
 - 4.4- Examples
- V- Counting Process
- VI- Accumulation (Loops) Process
- VII- String Variables Manipulation
- VIII- Subroutines
- IX- Functions
- X- Introduction to Databases

Laboratory

Programming in Basic or Pascal using the VAX/VMS computer system.

TE231 Electric Circuits and Machines

Year : two

Semesters: 03 and 04

Credit/Lec./Rec./Lab. 4/3/1.5/1.5

- I- Theorems in AC Circuits
- II- Power in AC Circuits
- III- Series and Parallel Resonance
- IV- Three-Phase Circuits
- V- Fourier Series
- VI- Mutual Inductance
- VII- Z, Y and H Parameters
- VIII- Polyphase Systems
 - 8.1- Review of basic principles: methods of interconnection, evaluation of voltage and current, power and methods of measurements
 - 8.2- Introduction to 6-phase and 12-phase systems
- IX- Power Components and Circuits
 - 9.1- Performance characteristics
 - 9.2- Power transmission line
- X- Introduction to Machines
- XI- Machine Operation (as a load not a study of construction)
 - 11.1- Principles of operation
 - 11.2- Circuit diagram representation
 - 11.3- DC and AC characteristic curves
 - 11.4- DC motors: shunt, series, compound, servo, permanent magnet, split field
 - 11.5- AC motors: synchronous, universal, induction
 - 11.6- Digital: stepping
- XII- Machine Control Principles
 - 12.1- Direction of rotation
 - 12.2- Speed
 - 12.3- DC output voltages and polarity
 - 12.4- AC output voltages, frequency and phase
 - 12.5- Starting and stopping
 - 12.6- Machine control terminology: adjustable drive, asynchronous, braking, inching, jogging, plugging, pull-in torque, reversing, slip, synchronous, torque

- XIII- Protection
 - 13.1- Common fault conditions
 - 13.2- Descriptive treatment of fault determination and elimination of counteraction
- XIV- Transducers
 - 14.1- Transducers used in the control of electric machines
 - 14.2- Application of typical transducers

- 1- Power in AC circuits
- 2- Series and parallel resonance
- 3- 3-phase circuits
- 4- Transformer ad mutual inductance
- 5- Polyphase systems: watts, VARs, volt-amperes
- 6- Transformers:
 - 6.1- Regulation, auto-transformer, parallel connections
 - 6.2- Three-phase transformer, 3-phase to 2-phase conversion
- 7- Transmission line characteristics
- 8- Characteristics of machines
 - 8.1- DC motor
 - 8.2- Induction motor
 - 8.3- Capacitor start motor
 - 8.4- Universal motor
 - 8.5- Synchronous motor
- 9- Machine control performance
 - 9.1- Frequency conversion
 - 9.2- Speed control

TE291 Management

Year : two

Semesters: 03 and 04

Credit/Lec./Rec./Lab. 2/1.5/0/0

- I- Background of Production Management
- II- Basic Economic Concepts
- III- Equipment and Working Facilities
- IV- Procurement and Storage
- V- Production Planning and Control

TE224 Introduction to Computer Technology

Year: three Semester: 05 Option: Digital

Credit/Lec./Rec./Lab. 3/1.5/1.5/1.5

Reference book: PC Intern, Michael Tischer

Outline

- 1- Introduction to Computers
- II- Personal Computer Organization
- III- Central Processing Unit
- IV- Memory Organization
- V- Machine Language Programming: the Debugger
- VI- Assembly Language Programming: MASM or TASM
- VII- Programming Examples
- VIII- Input-Output Handling
- IX- Interrupt Handling
- X- High Level Language Programming: C or Pascal Language

- 1- PC debugger: enter, edit and run a machine language program.
- 2- MASM or TASM assembly language programming
- 3- Debugging assembly language programs
- 4- C or Pascal programming

TE321 Microprocessors

Year: three Semester: 05

Option: Digital, Maintenance, Power

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook: The Z-80 Microprocesor, Ramesh S. Gaonkar, 3rd Edition.

- I- Introduction to Microprocessors
 - 1.1- Microprocessor History and Evolution
 - 1.2- Microcomputers and Large Frame Systems
 - 1.3- Microprocessor-Based Systems Architecture
 - 1.4- Microprocessor Architecture
 - 1.4-1. General computer architecture
 - 1.4-2. The MPU
 - 1.4-3. Input/Output
 - 1.4-4. A Comparison of Typical Microprocessors
- II- The Z-80 Microprocessor
 - 2.1- MPU Signal Description
 - 2.2- Programming Model
 - 2.3- Memory and I/O Interfacing
- III- Z-80 Assembly Language Programming
 - 3.1- Instruction Set and Machine Language Programming
 - 3.2- Addressing Modes
 - 3.3- Introduction to Z-80 Assembly Language and Programming
 - 3.4- Assemblers and Software Development Tools
 - 3.5- Stacks and Subroutines
 - 3.6- Programming Examples
- IV- Memory Interfacing
 - 4.1- MPU Timing Diagrams
 - 4.2- Timing Considerations of Memory Devices
 - 4.3- Memory Organization and Address Decoding
 - 4.4- Memory Expansion
 - 4.5- MT-80AZ Memory Map
- V- 1/O Interfacing
 - 5.1- Interrupt Handling Techniques
 - 5.2- Simple Input/Output Devices
 - 5.3- I/O Device selection
 - 5.4- Programmable Interface Devices:
 - 5.4-1. Intel PPI 8255
 - 5.4-2. Zilog Parallel Input Output (PIO)
 - 5.4-3. Zilog Counter Timer Circuit (CTC)



- VI- Direct Memory Access
 - 6.1- DMA Concepts
 - 6.2- The Z-80 DMA Structure
- VII- Microprocessor-Based Systems
 - 7.1- Application Examples
- VIII- Trends in Microprocessors Technology

LAB. EXPERIMENTS

- 1- Getting Familiar with the MT-80AZ Microcomputer
- 2- Arithmetic Operations
- 3- Data Conversion and Manipulations-
- 4- Event Counting and Interrupt Handling
- 5- I/O Interfacing through the 8255 PPI
- 6- Waveform Generation (DACs Interfacing)
- 7- Data Acquisition (ADC Interfacing)

3rd Year Program

Semesters 05 and 06

Digital Option

TE322 Digital Systems Troubleshooting

Year: three Semester: 05 Option: Digital

Credit/Lec./Rec./Lab. 2/1.5/0/3

Outline

- 1- Introduction
 - 1.1- Component failure
 - 1.2- IC testing
- II- Digital Measurements
 - 2.1- General consideration
 - 2.2- Digital signal characteristics
 - 2.3- Digital probe application techniques
 - 2.4- Digital multimeter
- III- The Logic Analyzer
 - 3.1- Complete study of the logic analyzer (available type)
 - 3.2- Applications
- IV- Testing the Microprocessor
- V- Trouble shooting System Failure

TE324 Programmable Controllers

Year: three Semester: 05 Option: Digital

Credit/Lec./Rec./Lab. 3/1.5/1.5/1.5

Textbook: Programmable Logic Controllers.

- I- Introduction to PLCs
 - 1.1- Microprocessors evolution
 - 1.2- Micro-controllers
 - 1.3- Application Specific ICs (ASICs)
 - 1.4- Application of PLCs
- II- PLC Architecture
 - 2.1- Example Architectures
 - 2.2- Logic Circuitry
 - 2.3- 1/O Ports
 - 2.4- RAM/EPROM
 - 2.5- Power Interface
- III- Introduction to Programming
 - 3.1- Instruction Set
 - 3.2- Ladder Diagram
 - 3.3- Programming Examples
- IV- Advanced PLC Functions
 - 4.1- Ladder Diagram Simplification
 - 4.2- Advanced Functions (Timing, Delay)
 - 4.3- Power Interfacing
- V- Advanced PLC Programming
 - 5.1- Problem specification
 - 5.2- Problem solving

TE332 Power Electronics

Year: three Semester: 05

Option: Digital, Maintenance, Power

Credit/Lec./Rec./Lab. 3/1.5/1.5/1.5

Textbook:

- 1- Introduction to Power Electronics
 - 1.1- Definition of power electronics
 - 1.2- Types of power switches used
 - 1.3- Converter terminology
 - 1.4- Power frequency domains
- II- Power Devices
 - 2.1- Power rectifier: thyristor, TRIAC, gate turn-off switch
 - 2.2- Power devices characteristics and parameters
 - 2.3- Thermal performance under normal and fault conditions, heat sinks
 - 2.4- Gating requirements
- III- Power Rectification
 - 3.1- Single and 3-phase half wave, full wave center-tapped and bridge circuits
 - 3.2- Development of circuit operation and complete circuit waveforms with R, RL, back EMF loads
 - 3.3- Prediction of differences between ideal and practical circuits
 - 3.4- Operation and use of freewheeling diode
 - 3.5- Application areas
- IV- Controlled Rectification Principles
 - 4.1- Combination of silicon controlled rectifiers
 - 4.2- Phase control principles and the problems of firing (gating), RF interference, switching transients
 - 4.3- Properties and use of snubber circuits
 - 4.4- Graphical performance curves
- V- AC Voltage Control Principles
 - 5.1- Principles of phase control
 - 5.2- Comparison of operational characteristics of the systems
 - 5.3- Voltage, power and harmonic contents graphical performance curves
 - 5.4- Comparison of TRIAC with inverse-parallel SCR arrangement
- VI- DC-DC Converters
 - 6.1- Commutation in DC systems and circuits used to turn off SCR's
 - 6.2- Basic DC chopper circuit
- VII- Inverters
 - 7.1- Series and parallel single-phase inverters
 - 7.2- Filtering techniques used to improve output waveforms

- VIII- Frequency Changing: Cycloconverters and Cycloinverters
- IX- Power Factor Correction: Basic Networks
- X- Power Control Systems
 - 10.1- Motor speed control
 - 10.2- Lighting systems
 - 10.3- Heater controls
- XI- Protection Systems
 - 11.1- Generation and elimination of transients
 - 11.2- Protection of devices

- 1- Use of oscilloscope to display the major characteristics of SCR and TRIAC
- 2- Reverse-recovery current demonstration
- 3- Single-phase rectifier: half-wave with R, RL, back emf and freewheeling diode
- 4- Single-phase rectifier: switching transients, output parameters measurements, frequency spectrum demonstration
- 5- Phase shift networks
- 6- Single-phase AC control
- 7- DC commutation and chopper circuits
- 8- Parallel inverter
- 9- Light control circuits: DC flasher, AC flasher, ring counter, light dimmer
- 10- Motor speed control

TE318 Digital Communications

Year: three Semester: 06 Option: Digital

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook:

Outline

Introduction to Communication Systems

- 1.1- Communications
- 1.2- Communications systems: information, transmitter, channel noise, receiver
- 1.3- Modulation/demodulation
- 1.4- Bandwidth requirements

Noise

- 2.1- External noise
- 2.2- Internal noise
- III- Amplitude Modulation (AM)
 - 3.1- AM theory
 - 3.2- Generation of AM
- IV- Frequency Modulation (FM)
 - 4.1- Theory of frequency and phase modulation
 - 4.2- Generation of FM.
- V- Transmission Lines
- VI- Digital Communication Modes
 - 6.1- PCM
 - 6.2- FSK
 - 6.3- PSK
 - 6.4- Other modulation techniques
- .'II- Code Sets and Characters
 - 7.1- ASCII
 - 7.2- EBCDIC
 - 7.3- CCITT-V24
 - 7.4- Baudot
- III- Error Detection and Correction
 - 8.1- Control procedures
 - 8.2- Digital vs. Analog
 - 8.3- Bit characteristics
 - 8.4- Parity generation-checking
 - 8.5- The Hamming code

- IX- Modems and Interfacing
 - 9.1- Types
 - 9.2- Baud rates
 - 9.3- RS232-C interface, etc...
- X- Computer Communications
 - 10.1- Parallel vs. serial communication
 - 10.2- Terminal to computer interface
 - 10.3- Computer to computer interface
- . XI- Communication Protocols
 - 11.1- Message format and transfer
 - 11.2- Communication protocols

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TE323 Industrial Process Control

Year: three Semester: 06

Option: Digital, Maintenance

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook: Process Control Instrumentation Technology, Curtis D. Johnson, 3rd edition

- I- Introduction to Process Control
 - 1.1- Definition of process control
 - 1.2- Elements
 - 1.3- Evaluation of process control
 - 1.4- Analog vs. digital Configurations
 - 1.5- Transient functions
 - 1.6- Units, standards and definitions
- II- Transducers
 - 2.1- Definitions
 - 2.2- Signal conditioning
 - 2.2-1. Bridge circuits: null condition, current balance bridge
 - 2.2-2. Potentiometer circuits
 - 2.2-3. Active circuits: op-amps inverting, non-inverting, summing, V-I and I-V converters, integrator, sample-and-hold
 - 2.3- Thermal transducers
 - 2.4- Optical transducers
 - 2.5- Physical transducers
 - 2.5-1. Displacement
 - 2.5-2. Pressure
 - 2.5-3. Flow, level
- III- Final Control Elements
 - 3.1- Principles
 - 3.1-1. Signal conversion
 - 3.1-2. Actuator
 - 3.1-3. Final control device
 - 3.2- Examples of final controls
 - 3.2-1. Electric actuators
 - 3.2-2. Control valves
- IV- Controllers
 - 4.1- Definitions
 - 4.2- Discontinuous controller modes
 - 4.2-1. Two-position control
 - 4.2-2. Multiple position
 - 4.2-3. Floating

- 4.3- Continuous controller modes
 - 4.3-1. Proportional mode
 - 4.3-2. Integral mode
 - 4.3-3. Derivative mode
- 4.4- Composite controller modes
- 4.5- Analog vs. digital systems
- V- Control Loops
 - 5.1- Configurations: single variable, cascade
 - 5.2- Stability and quality: feedback gain and phase, cyclic response
 - 5.3- Loop tuning
 - 5.3-1. Transient response
 - 5.3-2. Ziegler-Nichols chart
 - 5.3-3. Frequency response
- VI- Data Acquisition
 - 6.1- Hardware: comparators, DAC, ADC, DAS, microprocessors
 - 6.3- Software: format, input data operation, controller modes, time delays, function generation, microprocessor interrupt handling.
- VII- Computers in Process Control
 - 7.1- Programmable controllers
 - 7.2- Digital data acquisition systems (DDAS)
 - 7.3- Supervisory control
 - 7.4- Direct digital control (DDC)
 - 7.5- Characteristics of digital data.

- 1- Z80 Based Microcomputer, Comparators, DAC, ADC, Computer signal generation, two position control, temperature control.
- 2- PLC FX0s-based experiments

TE325 Special Topic on Computers

Year: three Semester: 06 Option: Digital

Credit/Lec./Rec./Lab. 3/1.5/0/1.5

Textbook:

Outline

Topics: choose one of the following

- 1- Artificial Intelligence
- 2- Graph Theory
- 3- Matlab
- 4- Computer Networks
- 5- Etc...

TE312 Electronic Communications

Year: three Semester: 05

Option: Maintenance

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook:

- 1- Introduction to Communication Systems
- II- RF Amplifiers
 - 2.1- Tuned RF amplifiers
 - 2.2- Neutralization
 - 2.3- Special RF amplifiers
 - 2.4- Frequency conversion and mixers
 - 2.5- Intermediate frequency (IF) amplifiers
 - 2.6- Transmitter and amplifier matching
- III- Amplitude Modulation (AM)
 - 3.1- Introduction
 - 3.2- Mathematical description
 - 3.3- Frequency spectrum
 - 3.4- Power content
 - 3.5- Single side band (SSB) and double side band (DSB) techniques
 - 3.6- Generation of AM
- IV- Frequency Modulation (FM)
 - 4.1- Theory of FM and phase modulation (PM)
 - 4.2- Percent modulation
 - 4.3- Center frequency and band width (BW) allocation, deviation ratio
 - 4.4- Generation of FM
- V- Receivers
 - 5.1- Demodulation
 - 5.2- Detection of AM and FM
 - 5.3- Super heterodyne receivers
 - 5.4- Automatic gain control (AGC)
 - 5.5- Automatic frequency control (AFC)
 - 5.6- Amplitude limiters
 - 5.7- Radio and TV receivers
- VI- Transmitters
 - 6.1- Introduction
 - 6.2- AM transmitters
 - 6.3- FM transmitters
 - 6.4- Radio and TV transmitters

- VII- Transmission Line
 - 7.1- Introduction
 - 7.2- Primary line constants
 - 7.3- Phase velocity and line wavelength
 - 7.4- Characteristic impedance
 - 7.5- Reflected wave and standing wave ratio (SWR)
 - 7.6- Reflected power
 - 7.7- Telephone line and cable
- VIII- Radiation and Propagation of Waves
 - 8.1- Electromagnetic radiation
 - 8.2- Propagation in free space
 - 8.3- Tropospheric and ionospheric propagation
- IX- Antenna Fundamentals
 - 9.1- Isotropic radiation
 - 9.2- Polar diagram
 - 9.3- Antenna power gain or directivity
 - 9.4- Vertical antennas
 - 9.5- Folded elements
 - 9.6- VIIF and UIIF antennas
- X- Noise
 - 10.1- External noise
 - 10.2- Internal noise
 - 10.3- Noise calculation
 - 10.4- Noise figure
 - 10.5- Noise temperature

- 1- Hartley oscillator
- 2- Audio pre-amplifier, driver and output stage
- 3- Super heterodyne 1st and 2nd amplifier stage
- 4- Amplitude modulation and demodulation
- 5- Super heterodyne detector and AVC stage
- 6- Super heterodyne converter stage
- 7- RF amplifier
- 8- FM, detection principles
- 9- AFC principles
- 10- Varactor diode
- 11-Beat frequency principles

TE321 Microprocessors

Year: three Semester: 05

Option: Digital, Maintenance, Power

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook: The Z-80 Microprocesor, Ramesh S. Gaonkar, 3rd Edition.

Outline

1- Introduction to Microprocessors

- 1.1- Microprocessor History and Evolution
- 1.2- Microcomputers and Large Frame Systems
- 1.3- Microprocessor-Based Systems Architecture
- 1.4- Microprocessor Architecture
 - 1.4-1. General computer architecture
 - 1.4-2. The MPU
 - 1.4-3. Input/Output
 - 1.4-4. A Comparison of Typical Microprocessors

II- The Z-80 Microprocessor

- 2.1- MPU Signal Description
- 2.2- Programming Model
- 2.3- Memory and I/O Interfacing

III- Z-80 Assembly Language Programming

- 3.1- Instruction Set and Machine Language Programming
- 3.2- Addressing Modes
- 3.3- Introduction to Z-80 Assembly Language and Programming
- 3.4- Assemblers and Software Development Tools
- 3.5- Stacks and Subroutines
- 3.6- Programming Examples

IV- Memory Interfacing

- 4.1- MPU Timing Diagrams
- 4.2- Timing Considerations of Memory Devices
- 4.3- Memory Organization and Address Decoding
- 4.4- Memory Expansion
- 4.5- MT-80AZ Memory Map

V- I/O Interfacing

- 5.1- Interrupt Handling Techniques
- 5.2- Simple Input/Output Devices
- 5.3- I/O Device selection
- 5.4- Programmable Interface Devices:
 - 5.4-1. Intel PPI 8255
 - 5.4-2. Zilog Parallel Input Output (PIO)
 - 5.4-3. Zilog Counter Timer Circuit (CTC)

- VI- Direct Memory Access
 - 6.1- DMA Concepts
 - 6.2- The Z-80 DMA Structure
- VII- Microprocessor-Based Systems
 - 7.1- Application Examples
- VIII- Trends in Microprocessors Technology

LAB. EXPERIMENTS

- 1- Getting Familiar with the MT-80AZ Microcomputer
- 2- Arithmetic Operations
- 3- Data Conversion and Manipulations
- 4- Event Counting and Interrupt Handling
- 5- I/O Interfacing through the 8255 PPI
- 6- Waveform Generation (DACs Interfacing)
- 7- Data Acquisition (ADC Interfacing)

TE332 Power Electronics

Year: three Semester: 05

Option: Digital, Maintenance, Power

Credit/Lec./Rec./Lab. 3/1.5/1.5/1.5

Textbook:

- I- Introduction to Power Electronics
 - 1.1- Definition of power electronics
 - 1.2- Types of power switches used
 - 1.3- Converter terminology
 - 1.4- Power frequency domains
- II- Power Devices
 - 2.1- Power rectifier: thyristor, TRIAC, gate turn-off switch
 - 2.2- Power devices characteristics and parameters
 - 2.3- Thermal performance under normal and fault conditions, heat sinks
 - 2.4- Gating requirements
- III- Power Rectification
 - 3.1- Single and 3-phase half wave, full wave center-tapped and bridge circuits
 - 3.2- Development of circuit operation and complete circuit waveforms with R. RL. back EMF loads
 - 3.3- Prediction of differences between ideal and practical circuits
 - 3.4- Operation and use of freewheeling diode
 - 3.5- Application areas
- IV- Controlled Rectification Principles
 - 4.1- Combination of silicon controlled rectifiers
 - 4.2- Phase control principles and the problems of firing (gating), RF interference, switching transients
 - 4.3- Properties and use of snubber circuits
 - 4.4- Graphical performance curves
- V- AC Voltage Control Principles
 - 5.1- Principles of phase control
 - 5.2- Comparison of operational characteristics of the systems
 - 5.3- Voltage, power and harmonic contents graphical performance curves
 - 5.4- Comparison of TRIAC with inverse-parallel SCR arrangement
- VI- DC-DC Converters
 - 6.1- Commutation in DC systems and circuits used to turn off SCR's
 - 6.2- Basic DC chopper circuit
- VII- Inverters
 - 7.1- Series and parallel single-phase inverters
 - 7.2- Filtering techniques used to improve output waveforms

- VIII- Frequency Changing: Cycloconverters and Cycloinverters
- IX- Power Factor Correction: Basic Networks
- x- Power Control Systems
 - 10.1- Motor speed control
 - 10.2- Lighting systems
 - 10.3- Heater controls
- XI- Protection Systems
 - 11.1- Generation and elimination of transients
 - 11.2- Protection of devices

- 1- Use of oscilloscope to display the major characteristics of SCR and TRIAC
- 2- Reverse-recovery current demonstration
- 3- Single-phase rectifier: half-wave with R, RL, back emf and freewheeling diode
- 4- Single-phase rectifier: switching transients, output parameters measurements, frequency spectrum demonstration
- 5- Phase shift networks
- 6- Single-phase AC control
- 7- DC commutation and chopper circuits
- 8- Parallel inverter
- 9- Light control circuits: DC flasher, AC flasher, ring counter, light dimmer
- 10- Motor speed control

TE345 Electronic Troubleshooting and Methodology

Year: three Semester: 05

Option: Maintenance

Credit/Lec./Rec./Lab. 4/3/0/3 Textbook:

- I- Introduction to Troubleshooting
 - 1.1- Overall troubleshooting procedure
 - 1.2- Relationship among troubleshooting steps
 - 1.3- Modification of the troubleshooting procedure
- II- Electrical Safety
 - 2.1 General electric safety
 - 2.2 Technician safety
 - 2.3 Measurement of current leakage
 - 2.4 The three-wire grounded outlet
 - 2.5 Further wiring safety considerations
 - 2.6 Equipment for safety measurements
- III- Determining Trouble Symptoms
 - 3.1- Knowing the equipment
 - 3.2- Use of operations controls during troubleshooting
 - 3.3- Recognizing trouble symptoms
 - 3.4- Equipment failure versus degraded performance
 - 3.5- Evaluation of symptoms
- IV- Localizing Trouble to a Functional Unit
 - 4.1- Meaning of "localize" in troubleshooting
 - 4.2- Functional divisions of equipment
 - 4.3- Functional block diagrams
 - 4.4- Bracketing technique
 - 4.5- Modifying the trouble-localization sequence
 - 4.6- Verifying trouble symptoms
- V- Isolating Trouble to a Circuit
 - 5.1- Servicing block diagrams
 - 5.2- Signal paths
 - 5.3- Signal tracing versus signal substitution
 - 5.4- Half-split technique
 - 5.5- Isolating trouble to a circuit within a circuit group
- VI- Localizing a Specific Trouble
 - 6.1- Locating trouble in plug-in modules
 - 6.2- Inspection using the senses
 - 6.3- Testing to locate a faulty component
 - 6.4- Waveform measurements

- Voltage measurements 6.5-
- Resistance measurements (1.(1-
- Using schematic diagrams 6.7-
- Internal adjustment during trouble localization 6.8-
- Trouble resulting from more than one fault 6.9-
- Repairing troubles 6.10-
- Operational check-out 6.11-

Solid-state Servicing Techniques VII-

- Measuring voltages in circuits 7.1-
- Troubleshooting with transistor voltages 7.2-
- Testing transistors in circuits (forward-bias method) 7.3-
- Using transistor testers 7.4-
- Testing transistors out of circuits 7.5-
- Testing diodes out of circuits 7.6-
- Effects of capacitors in troubleshooting 7.7-
- Effects on voltage of poor solder joints 7.8-

Amplifier Troubleshooting VIII-

- Basic amplifier troubleshooting 8.1-
- Checking distortion by sine-wave display 8.2-
- Background noise measurement 8.3-
- Feedback amplifier troubleshooting procedures 8.4-
- Effects of transistor leakage current on amplifier gain 8.5-
- Example of audio amplifier troubleshooting 8.6-

- 1- Demonstration of troubleshooting equipment and use
- 2- Using troubleshooting equipment for measuring important quantities, and observing signal waveforms.
- 3- Using troubleshooting trainer equipment with troubles set up by the instructor, the student should determine the trouble in a systematic way.
 - Determine the trouble symptoms 3.1-
 - Localize the trouble to a functional unit 3.2-
 - Isolate the trouble to a circuit 3.3-
 - Locate and repair the trouble 3.4-
 - Make a final operational checkout to ensure all the symptoms are repaired. 3.5-
 - 4- Testing transistors and diodes in and out of circuit
- 5- Use a faulty audio amplifier, follow the step-by-step procedure, see 3 above, to determine, localize and repair the failures one at a time.

TE351 Instrumentation and Measurement

Year: three Semester: 05

Option: Maintenance

Credit/Lec./Rec./Lab. 4/3/0/1.5 Textbook:

- 1- Measurement and Error
 - 1.1- Systems of units of measurement
 - 1.2- Definitions
 - 1.3- Accuracy and precision
 - 1.4- Significant figures
 - 1.5- Types of errors
 - 1.6- Statistical analysis
 - 1.7- Probability of errors
 - 1.8- Limiting errors
- II- Principles and Operation of Potentiometers
 - 2.1- Introduction
 - 2.2- Potentiometer circuits
 - 2.3- Volt box
 - 2.4- Shunt box
 - 2.5- Null detectors
 - 2.6- Calibrations of voltmeters and ammeters
 - 2.7- Self balancing potentiometers:
- III- DC Bridges and their Application
 - 3.1- Wheatstone bridge
 - 3.2- Kelvin bridge
 - 3.3- Loop tests
 - 3.4- Guarded Wheatstone bridge
- IV- AC Bridges and their Application
 - 4.1- General form of the AC bridge
 - 4.2- Comparison of bridges
 - 4.3- Maxwell bridge
 - 4.4- Hay bridge
 - 4.5- Schering bridge
 - 4.6- Unbalance conditions
 - 4.7- Wien bridge
 - 4.8- Wagner ground connection
 - 4.9- Universal impedance bridge



V- Oscilloscopes

- 5.1- Basic cathode-ray tube (CRT) principles
- 5.2- Horizontal time base
- 5.3- Horizontal deflection by sine wave voltage
- 5.4- The sweep generating circuit
- 5.5- General purpose oscilloscope
- 5.6- Lissajous figures
- 5.7- Special purpose oscilloscopes

VI- Signal Generators

- 6.1- Types of generated signals
- 6.2- Audio frequency oscillator
- 6.3- Radio frequency oscillator
- 6.4- Function generators
- 6.5- Wave form analysis

VII- Integrated Circuits

- 7.1- Introduction to ICs used in instrumentation
- 7.2- Circuit function
- 7.3- Examples of digital, linear and op-amp integrated circuits
- 7.4- Types of linear integrated circuits
- 7.5- Examples of typical IC application

VIII- Analog and digital data Acquisition Systems

- 8.1- Instrumental systems
- 8.2- Digital to analog conversion
- 8.3- Analog to digital conversion
- 8.4- Magnetic tape recorders

IX- Digital Voltmeter, Ammeter and Ohmmeter

- 9.1- Introduction
- 9.2- Digital multimeter
- 9.3- Considerations in choosing a digital multimeter

X- Electronic counters and their Application

- 10.1- Elements of the electronic counter
- 10.2- Decade counting systems
- 10.3- Time base and associated circuitry
- 10.4- Logic circuits
- 10.5- Universal counter

TE323 Industrial Process Control

Year: three Semester: 06

Option: Digital, Maintenance

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook: Process Control Instrumentation Technology, Curtis D. Johnson, 3rd edition

Outline

I- Introduction to Process Control

- 1.1- Definition of process control
- 1.2- Elements
- 1.3- Evaluation of process control
- 1.4- Analog vs. digital Configurations
- 1.5- Transient functions
- 1.6- Units, standards and definitions

11- Transducers

- 2.1- Definitions
- 2.2- Signal conditioning
 - 2.2-1. Bridge circuits: null condition, current balance bridge
 - 2.2-2. Potentiometer circuits
 - 2.2-3. Active circuits: op-amps inverting, non-inverting, summing, V-I and I-V converters, integrator, sample-and-hold
- 2.3- Thermal transducers
- 2.4- Optical transducers
- 2.5- Physical transducers
 - 2.5-1. Displacement
 - 2.5-2. Pressure
 - 2.5-3. Flow, level

III- Final Control Elements

- 3.1- Principles
 - 3.1-1 Signal conversion
 - 3.1-2 Actuator
 - 3.1-3 Final control device
- 3.2- Examples of final controls
 - 3.2-1. Electric actuators
 - 3.2-2. Control valves

IV- Controllers

- 4.1- Definitions
- 4.2- Discontinuous controller modes
 - 4.2-1. Two-position control
 - 4.2-2. Multiple position
 - 4.2-3. Floating

- 4.3- Continuous controller modes
 - 4.3-1. Proportional mode
 - 4.3-2. Integral mode
 - 4.3-3. Derivative mode
- 4.4- Composite controller modes
- 4.5- Analog vs. digital systems

V- Control Loops

- 5.1- Configurations: single variable, cascade
- 5.2- Stability and quality: feedback gain and phase, cyclic response
- 5.3- Loop tuning
 - 5.3-1. Transient response
 - 5.3-2. Ziegler-Nichols chart
 - 5.3-3. Frequency response

VI- Data Acquisition

- 6.1- Hardware: comparators, DAC, ADC, DAS, microprocessors
- 6.2- Software: format, input data operation, controller modes, time delays, function generation, microprocessor interrupt handling.

VII- Computers in Process Control

- 7.1- Programmable controllers
- 7.2- Digital data acquisition systems (DDAS)
- 7.3- Supervisory control
- 7.4- Direct digital control (DDC)
- 7.5- Characteristics of digital data.

- 1- Z80-Based Microcomputer, Comparators, DAC, ADC, Computer signal generation, two-position control, temperature control.
- 2- PLC FX0s-based experiments

TE352 Electronic Equipment Troubleshooting

Year: three Semester: 06

Option: Maintenance

Credit/Lec./Rec./Lab. 2/3/0/0

Textbook:

Outline

- 1- Power Supply
- II- Analog Multimeter
- III- Digital Multimeter
- IV- Function Generator
- V- RF Generator
- VI- Frequency Counter
- VII- Oscilloscope
- VIII- Radio Receiver Troubleshooting
- IX- Introduction to television
- X- Black and White Troubleshooting and Repair
- XI- Color TV Fundamentals
- XII- Color TV Troubleshooting

- 1- Power supply: adjustment and calibration, troubleshooting
- 2- Analog multimeter: adjustment and calibration, troubleshooting
- 3- Digital multimeter: adjustment and calibration, troubleshooting
- 4- Function generator: adjustment and calibration, locating troubles
- 5- RF generator: identification of sections, adjustment and calibration, troubleshooting
- 6- Frequency counter: identification of sections, adjustment and calibration, troubleshooting
- 7- Oscilloscope: adjustment and calibration, troubleshooting and test equipment
- 8- The super heterodyne receiver: identification of sections: AM, FM, Audio amplifier, power supply, waveforms and voltage monitoring.
- 9- Signal injection and tracing tests, alignment procedures
- 10-TV troubleshooting techniques and test instruments: DC voltage measurements, oscilloscope measurement, black and white and color bar generator
- 11-Faults in video amplifiers
- 12- Checking high voltage power supplies

3rd Year Program

Semesters 05 and 06

Power Option

TE321 Microprocessors

Year: three Semester: 05

Option: Digital, Maintenance, Power

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook: The Z-80 Microprocesor, Ramesh S. Gaonkar, 3rd Edition.

- 1- Introduction to Microprocessors
 - 1.1- Microprocessor History and Evolution
 - 1.2- Microcomputers and Large Frame Systèms
 - 1.3- Microprocessor-Based Systems Architecture
 - 1.4- Microprocessor Architecture
 - 1.4-1. General computer architecture
 - 1.4-2. The MPU
 - 1.4-3. Input/Output
 - 1.4-4. A Comparison of Typical Microprocessors
- II- The Z-80 Microprocessor
 - 2.1- MPU Signal Description
 - 2.2- Programming Model
 - 2.3- Memory and I/O Interfacing
- III- Z-80 Assembly Language Programming
 - 3.1- Instruction Set and Machine Language Programming
 - 3.3- Addressing Modes
 - 3.4- Introduction to Z-80 Assembly Language and Programming
 - 3.5- Assemblers and Software Development Tools
 - 3.6- Stacks and Subroutines
 - 3.7- Programming Examples
- IV- Memory Interfacing
 - 4.1- MPU Timing Diagrams
 - 4.2- Timing Considerations of Memory Devices
 - 4.3- Memory Organization and Address Decoding
 - 4.4- Memory Expansion
 - 4.5- MT-80AZ Memory Map
- V- I/O Interfacing
 - 5.1- Interrupt Handling Techniques
 - 5.2- Simple Input/Output Devices
 - 5.3- I/O Device selection
 - 5.4- Programmable Interface Devices:
 - 5.4-1. Intel PPI 8255
 - 5.4-2. Zilog Parallel Input Output (PIO)
 - 5.4-3. Zilog Counter Timer Circuit (CTC)

- VI- Direct Memory Access
 - 6.1- DMA Concepts
 - 6.2- The Z-80 DMA Structure
- VII- Microprocessor-Based Systems
 - 7.1- Application Examples
- VIII- Trends in Microprocessors Technology

LAB. EXPERIMENTS

- 1- Getting Familiar with the MT-80AZ Microcomputer
- 2- Arithmetic Operations
- 3- Data Conversion and Manipulations
- 4- Event Counting and Interrupt Handling
- 5- I/O Interfacing through the 8255 PPI
- 6- Waveform Generation (DACs Interfacing)
- 7- Data Acquisition (ADC Interfacing)

TE331 Power System Components

Year: three Semester: 05 Option: Power

Credit/Lec./Rec./Lab. 4/3/0/1.5

Textbook:

Outline

I- Polyphase Circuits .

- 1.1- Three-phase voltages
- 1.2- Three and four-wire wye (Y) systems
- 1.3- Three-wire delta systems
- 1.4- Delta-Wye (Λ-Y) conversion power
- 1.5- Balanced and unbalanced system calculations
- 1.6- Power measurements

II- Transformers

- 2.1- Review of magnetic circuits
- 2.2- Construction of transformers
- 2.3- The ideal transformer
- 2.4- Equivalent circuits
- 2.5- Voltage regulation
- 2.6- Open circuits and short circuit tests
- 2.7- Efficiency calculations

III- Transformer Types

- 3.1- Multiple windings
- 3.2- Auto-transformer
- 3.3- Instrument transformers: current, potential

IV- Transformer Connections

- 4.1- Series
- 4.2- Parallel
- 4.3- Three-phase: Y-Y, Y-A, A-A
- 4.4- Scott connection
- 4.5- V-connection
- 4.6- Polyphase connections for 6, 9 and 12 phases
- 4.7- Vector group of three-phase transformers

V- Circuit Breakers

- 5.1- Construction and operation of
 - 5.1-1. Oil circuit breakers
 - 5.1-2. Air break
 - 5.1-3. Air blast
 - 5.1-4. Semiconductor circuit breakers
- 5.2- Specifications, testing, maintenance and safety of circuit breakers

- VI- Electromechanical Devices
 - 6.1- Relays
 - 6.2- Contactors
 - 6.3- Timers

- 1- Measurement of the power factor (PF) of an inductive load. Use of a capacitor to correct the PF of a large inductive load.
- 2- Power consumption in Y and Δ connected balanced loads, measure line and phase currents
- 3- Measure power in a 4-wire balanced and unbalanced Y load, measure line, phase and neutral currents
- 4- Power measurement by three and two-wattmeter method
- 5- Single-phase transformer parameters, open circuit and short circuit tests
- 6- Transformer efficiency
- 7- Polarity test of a transformer
- 8- Parallel operation of single phase transformers
- 9- Characteristics of an auto-transformer
- 10- Getting two-phase supply from a balanced three-phase Scott-connection supply
- 11-Three-phase transformer connection
- 12-Load test on transformer to determine voltage regulation.

TE332 Power Electronics

Year: three Semester: 05

Option: Digital, Maintenance, Power

Credit/Lee./Ree./Lab. 3/1.5/1.5/1.5

Textbook:

Outline

1-Introduction to Power Electronics

- Definition of power electronics
- 1.2-Types of power switches used
- 1:3-Converter terminology
- 1.4-Power frequency domains

11-Power Devices

- Power rectifier: thyristor, TRIAC, gate turn-off switch 2.1-
- Power devices characteristics and parameters 2.2-
- Thermal performance under normal and fault conditions, heat sinks 2.3-
- 2.4-Gating requirements

111-Power Rectification

- Single and 3-phase half wave, full wave center-tapped and bridge circuits 3.1-
- Development of circuit operation and complete circuit waveforms with R, RL, 3.2back EMF loads
- Prediction of differences between ideal and practical circuits 3.3-
- Operation and use of freewheeling diode 3.4-
- 3.5-Application areas

Controlled Rectification Principles

- Combination of silicon controlled rectifiers 4.1-
- Phase control principles and the problems of firing (gating), RF interference. 4.2switching transients
- Properties and use of snubber circuits 4.3-
- Graphical performance curves 4.4-

V-AC Voltage Control Principles

- 5.1-Principles of phase control
- Comparison of operational characteristics of the systems 5.2-
- 5.3-Voltage, power and harmonic contents graphical performance curves
- 5.4-Comparison of TRIAC with inverse-parallel SCR arrangement

VI-DC-DC Converters

- Commutation in DC systems and circuits used to turn off SCR's 6.1-
- 6.2-Basic DC chopper circuit

VII-Inverters

- 7.1-Series and parallel single-phase inverters
- Filtering techniques used to improve output waveforms 10.4-

- VIII- Frequency Changing: Cycloconverters and Cycloinverters
- IX- Power Factor Correction: Basic Networks
- X- Power Control Systems
 - 10.1- Motor speed control
 - 10.2- Lighting systems
 - 10.3- Heater controls
- XI- Protection Systems
 - 11.1- Generation and elimination of transients
 - 11.2- Protection of devices

- 1- Use of oscilloscope to display the major characteristics of SCR and TRIAC
- 2- Reverse-recovery current demonstration
- 3- Single-phase rectifier: half-wave with R, RL, back EMF and freewheeling diode
- 4- Single-phase rectifier: switching transients, output parameters measurements, frequency spectrum demonstration
- 5- Phase shift networks
- 6- Single-phase AC control
- 7- DC commutation and chopper circuits
- 8- Parallel inverter
- 9- Light control circuits: DC flasher, AC flasher, ring counter, light dimmer
- 10- Motor speed control

TE333 Electric Machines

Year: three Semester: 05 Option: Power

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook:

- Paralleling of DC Generators 1-
 - 1.1-Requirements
 - Parallel shunt and compound generators: identical and different units 1.2-
 - 1.3-Equalizer connections
- Paralleling of Synchronous Generators 11-
 - 2.1-Requirements
 - 2.2-Synchronizing power and torque
 - 2.3-Synchronizing procedure
 - 2.4-Lamp and synchroscope methods
- 111-Synchronous Motor
 - 3.1-Power factor control
 - 3.2-Operation as synchronous capacitor
 - 3.3-Vector diagrams
 - Economical limit of PF improvement 3.4-
 - 3.5-Starting methods
- IV-Single Phase Induction Motors
 - 4.1-Starting
 - 4.2-Operation with double revolving field theory
 - 4.3-Split phase
 - 4.4-Capacitor start
 - 4.5-Capacitor run
 - Auto-transformer and capacitor type motors with operation and characteristics 4.6-
 - 4.7-Motor efficiency
 - 4.8-Tests
 - 4.9-Reversing
- Shaded Pole, Universal Motors
 - 5.1-Construction
 - 5.2-Operation
 - 5.3-Reversing and efficiency
 - 5.4-Other single phase motors
- AC Motor Control and Operation
 - 6.1-General load characteristic consideration
 - 6.2-Starting
 - 6.3-Reversing
 - 6.4-Plugging and speed control with various methods

- VII- Motor selection
 - 7.1- Investigation on factors of selection
- VIII- Special Use of Synchronous and Induction Machines
 - 8.1- Frequency converter
 - 8.2- Phase converter
 - 8.3- Induction regulators
- IX- Special DC Machines
 - 9.1- Amplydyne
 - 9.2- Rösenberg generator
 - 9.3- Rototrol
 - 9.4- Regulex

TE336 Electric Layout and Design

Year: three Semester: 05 Option: Power

Credit/Lec./Rec./Lab. 4/3/0/3 Textbook:

Outline

- I- Design Considerations
 - 1.1- Electrical construction drawing
 - 1.2- Electrical diagrams
 - 1.3- Block diagrams
 - 1.4- One-line diagram
- II- Lighting
 - 2.1- Definition
 - 2.2- Spectrum
 - 2.3- Characteristics
 - 2.4- Sources
 - 2.5- Brightness
 - 2.6- Glare
 - 2.7- Lamps: types, operation and circuit
- III- Non-Lighting Electrical Loads
 - 3.1- Home appliances
 - 3.2- Heaters, radiators, refrigerators
 - 3.3- Other specific loads
- IV- Standby Power Systems
- V- Conductors
 - 5.1- Types: copper, aluminum
 - 5.2- Solid conductors
 - 5.3- Stranded conductors
 - 5.4- Rubber and PVC installation.
- VI- Electrical Design Drawing

- 1- Load-dependent circuit design
- 2- Circuit breakers
- 3- Size of cables
- 4- Lighting
- 5- Power factor improvement

TE334 Power Generation, Transmission and Distribution

Year: three Semester: 06 Option: Power

Credit/Lec./Rec./Lab. 4/3/0/3

Textbook: Stevenson, Elements of Power System Analysis

- I- Energy Forms and Sources and Parameters Related in the Conversion
- II- Power Source Conversion
 - 2.1- Hydroelectric
 - 2.2- Wind
 - 2.3- Geothermal
 - 2.4- Solar
 - 2.5- Ocean power
- III- Energy Source conversion
 - 3.1- Nuclear
 - 3.2- Fossil fuel energy
- IV- Direct Generation
 - 4.1- MIID
 - 4.2- Fuel cell
 - 4.3- Thermoelectric
 - 4.4- Thermionic
- V- Steam Generation Systems
 - 5.1- Steam properties
 - 5.2- Steam turbine
 - 5.3- Heat generators
 - 5.4- Condenser
 - 5.5- Gasoline engine
 - 5.5-1. Thermodynamic cycles
 - 5.5-2. Carnot cycles
- VI- Energy Conversion and Management
- VII- Basic Concepts of Power Transmission
- VIII- Series Impedance of Transmission Lines
- IX- Capacitance of Lines
- X- Current and Voltage Relation on a Transmission Line
- XI- Representation of Power systems

- XII- Economic Operation and Load Flow
- XIII- Symmetrical Components
- XIV- Unsymmetrical Components
- XV- Short-circuit Calculations and Protection
- XVI- Power System Stability

Laboratory

- 1- Safety and the power supply
- 2- Phase sequence
- 3- Real power and reactive power
- 4- Power flow and reactive power
- 5- Phase angle and voltage drop between source and destination
- 6- Parameters affecting real and reactive power flow
- 7- Parallel lines, transformers and power handling capacity
- 8- Synchronous motor
- 9- Synchronous condenser and long high voltage lines
- 10- Transmission line networks and the Buck-Boost phase shifter.

Note: Field trips to power stations (eg. Cap-Djenet) and substations (eg. Boudouaou) are recommended.

TE335 Troubleshooting and Methodology

Year: three Semester: 06 Option: Power

Credit/Lee./Rec./Lab. 2/1.5/0/1.5 Textbook:

Outline

To be achieved by February 2002.

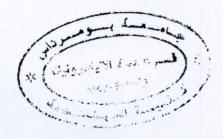
Ministry of Higher Education and Scientific Research



University "M'Hamed Bouguerra" of Boumerdes

Faculty of Engineering

Department of Electrical and Electronic Engineering (DGEE)



ENGLISH Program Guide

ENGLISH LANGUAGE DEPARTMENT GUIDE TO THE CURRICULUM

I INTRODUCTION

The English language curriculum is constructed in terms of semester. The following curriculum guide should prove useful in three ways:

- a) It can aid teachers in planning the syllabi for each course and in choosing the books for each course. By aiding in syllabus development, it provides a broadly standardized outline of what the department will teach each semester. It thus provides a basis of interaction between teachers of the same semester and across semesters. An overview of the programme is then established.
- b) It provides general parameters for the documentation of each course and to give some labels to parts of English lessons that will help standardize documentation.
- c) It provides categories for English lessons that will facilitate a well-organized Materials Bank.

The lists are ideal language proficiency objectives that relate to student activities carned on an English in the INELEC environment. One textbook will not necessarily fulfill all the objectives as they are stated. There are objectives that no textbook accomplishes; rather mixing and matching or creating materials will be appropriate. However, the objectives present the basic idea, and the suggested textbooks will be applicable to the goal. Audiotapes, video-tapes and films are used in the Language Laboratory (tape recorders) and Media Rooms to fulfill many of the listening (and speaking objectives). Some teacher creativity will be particularly necessary. It is hoped that each semester will provide instructor-created materials that are appropriate to the objectives, however, there is no expectation that one teacher or that one semester will fill all the gaps.

2. SEMESTER ONE (TO1: TS 111 and EO1: ES 111)

English 1: 24 contact hours divided as follows:

- 1) Reading and writing 6 hours
- II) Grunna Structure, 6 hours
- III) Listening and Speaking: 6 hours
- IV) Electricity Module (English for Electricity), o hours

2.1 Reading and writing

The following list is a sequence of objectives to be accomplished by the student-while focusing on reading and writing as language shalls. This first semester should provide a strong working base

Recognize and write the alphabet

Inow dictionary stalls: alphebetization

type face, abbreviations correct definition

use of examples parts of speech verb and noun forms

Practice punctuation fundamentals (continue throughout course)

Practice comprehension by reading aloud (sound-spelling recognition) and answering questions

Follow instructions

Laure a annulating saturation special

Identify paragraph organization : topic

main ideas

supporting details

Recognize the elements of discourse : chronological order

comparison/contrast appearance (description)

functional operation explanation definition

Be able to identify parts and/or objects from a description

Read and set up graphs

Scan

· Preview a text

· EST Tople Objectives

The following list is a chronological sequence of EST topics to be introduced to the first semester students. The list is long, but almost all concepts can be introduced first semester at a sentence and short paragraph level. The second semester will be used to deepen and lengthen the materials used. Terminology abounds in this area, so several variations for most concepts have been listed.

- 1. properties
 shapes
 measurement
 proportion/comparison and contrast
 frequency
- 2. location/position/direction structure/composition/partition
- function and ability movement and action/ agent
- 4 sequence/chronological order process/relationships other than chronological cause and effect / result classes method / following directions / instructions experiments / lab reports reporting observations / results / conclusions
- generalizations / induction-deduction probability
 hypothesis
- 6 defiration classification / division
- 7 fraphs and diagrams
- 8 word problems
- 9. explanations descriptions

The main objective of this list is to get the students acquainted with the special/technical language components they will need when communicating in their technical courses. Their introduction is not exclusively limited to the Reading and Writing course; they are rather treated on an integrative basis.

2.2 Listening and Speaking

The following list is a sequence of objectives to be accomplished by the student while focusing on listening and speaking as language skills. These skills are unportant since classroom learning is based on these abilities.

Pronounce letters and sounds (keyed to spelling)

Repeat words / sentences / pluases

Read aloud compreshensibly (sound-spelling coordination)

Ask for word meaning

Ask for information when something is not understood

Understand question forms . yes/no, wh-, affirmative-negative

Give information about a person-biographical details, activities

Practice intonation and pronunciation of questions, commands, and sentences

Produce inflectional endings (plurals, verb tense, etc.)

Recognize new words occurring within a mini-lecture by context and knowledge of roots and affixes

Recognize or supply correct vocabulary or grammatical form necessary in a focused listening text

Understand the description and function of an object

Discuss instruments or tools: parts, size, types, colors, materials and purposes.

Express simple desires

Make requests and commands (recognize difference)

Comprehend intonation and stress pattern that would occur withing a lecture

Be able to produce and understand the purpose of an instruction or command

Identify significant facts, main ideas and supporting evidence from a simple lecture with visual cues

Tell a simple narrative in the past

Relate future plans

Hear and define key subtechnical vocabulary within a listening text

Answer a problem with visuals as aids

Explain moving parts or changes

Ask specific questions about specific details: wh-, yes/no, either-or

Understand technical definitions given within a lecture

2.3 Grammar

Grammar Structures Objectives

The following alphabetical list of structures is a guideline for documenting and teaching the grammar to be included in this semester. The sequence of presentation depends on each separate course organization. If this list is completed before the semester ends, unnovation, review, and/or advanced grammar work is suggested.

Adjectives
Adjective phrases

Adverbial expression (with + NP, by + N, by + V + ing)
Adverbs of frequency
Adverbs of place and location/time/manner

Articles

Lic

Compansons

Compound nouns

Conditionals

Conjunctions

Demonstratives

DirecVinduect objects

Expletives (it, there in subject positions)

Gerunds

Indefinite pronouns (one, ones, other, etc.)

Intensifiers (very, too, enough, etc.)

Legical linkers

Mass and unit (how much/how many- count/non-count nouns)

Modals

Negatives.

Noun plurals

Participles (as adjectives)

Passive voice

Prepositions of place/position, time, manner Prepositional phrases

Pronowis

Punctuation

Qualifiers

Questions (wile, other, shortlong response)

Superlatives

Requests and Commands

Relative clauses (adjective-definition)

Verb tenses (simple present, present continuous, simple past, future, present perfect, past perfect)

Verbs: two-word separable/inseparable

Verbs: Special (say-tell, make-do, talk-speak, lay-lie, rise-raise, sit-set)

2.4 Electricity Module (English for Electricity)

Course: 4 hours Lab: 2 hours

Although the module is constructed on a subject syllabus, it treats the language on a topical structural basis. In addition to the technical and structural components, functional notions are introduced gradually to prepare students write definitions, descriptions, comparisons ...

a) Course Content

Introduction to Electricity

- ·The Importance of Electricity
- · Early History
- . What is Electricity.

Structure of Matter

- -What is Matter?
- -The Elements
- ·The compound
- The molecule
- -The Atem

Atomic Theory

- The structure of the Atom
- · The nucleus
- ·The proton
- -The electron

Electrical Charges

- -The law of electrical charges
- ·Atomic charges
- -Charged materials
- -Charging by contact and by induction
- ·Attraction and repulsion
- ·Electrostatic fields